

Novus Carry AGV Series



Automated Guided Vehicle (AGV)

Customized Solutions for Smart Assembly & Material Handling

Precision, Safety, and Efficiency in Every Move

What is an Automated Guided Vehicle (AGV)?

An Automated Guided Vehicle (AGV) is an advanced, driverless material-handling robot designed to transport heavy or delicate loads safely and efficiently within industrial environments. Guided by sensors, vision systems, LiDAR, or magnetic/QR navigation, AGVs automate repetitive movement tasks, reduce manual labor, and ensure consistent operational flow.


The Novus Carry AGV Series delivers high-performance intralogistics and assembly automation across multiple industries — with a strong focus on the automotive sector, where precision, payload capacity, and operational safety are critical for success.

Key Features of Novus Carry AGV Series

 Heavy-Duty Payload Handling

 Flexible Navigation Options

 Precision Docking

 Scalable & Modular

 Safety-First Design


 Low Maintenance, High Uptime


Industries We Serve


 Automotive

 Heavy Engineering

 Farm Equipment

 Electronics & Appliances


 Manufacturing & FMCG


 Aerospace




Use Cases of AGVs in the Automotive Industry

 Engine Assembly & Transfer


 Transmission Assembly

 Axle Assembly

 Instrument Panel/Digital Cluster Assembly

 Vehicle Marriage (body-to-chassis joining)

 Final Vehicle Assembly Line

 Trolley Transfer for component kits and sub-assemblies

Impact of Novus Carry AGV Series



Up to 30%
Faster Assembly
Line Efficiency



Reduced Manual
Labor & Lower
Operational Costs



Enhanced Workplace
Safety with zero-accident
movement



Industry 4.0 Integration
for smart factory
automation



Optimized Space
Utilization without
reliance on conveyors

Product Parameter

Navigation Type	Magnetic Tape/QR Code/SLAM(2D/3D)
Run direction	Uni/Bi/Omni
Load capacity	500 kg to 20 Ton (Custom Robot)
Travel speed	1 m/min to 30 m/min (Programmable as per JPH/Throughput)
Drive method.	Single Wheel / Differential / Ackermann (Steering) / Omnidirectional
Battery charging method	Manual Swapping / Opportunity Charging (Contact Type/Contactless Type) Induction Charging